

# M87\* IN SPACE, TIME AND FREQUENCY

## DYNAMIC VLBI IMAGING WITH INFORMATION FIELD THEORY

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Technical University TUM, Munich, Germany  
Max-Planck Institute for Astrophysics, Garching, Germany



# ACKNOWLEDGEMENTS

Our focus:

- ✦ Philipp Arras (TUM/MPA): radio imaging algorithms
- ✦ Jakob Knollmüller (TUM): approximate inference, machine learning
- ✦ Philipp Frank (LMU/MPA): statistical methods

Our co-authors:

- ✦ Philipp Haim (LMU/MPA): medical imaging
- ✦ Reimar Leike (LMU/MPA): galactic dust, machine learning
- ✦ Martin Reinecke (MPA): numerical algorithms
- ✦ Torsten Enßlin (MPA): head of *information field theory* group

LMU: Ludwig-Maximilians Universität München

TUM: Technical University Munich

MPA: Max-Planck Institute for Astrophysics, Garching

- ✦ The talk is structured into three main parts:
  1. Overview and results (Philipp Arras)
  2. Prior and likelihood (Philipp Frank)
  3. Inference scheme and validation (Jakob Knollmüller)
- ✦ The presentation material (including the videos) is available at:

<https://philipp-arras.de/2021cfa.html>
- ✦ Our paper [AFH<sup>+</sup>20] is available at:

<https://arxiv.org/abs/2002.05218>
- ✦ The imaging code is available under GPL license (see link in paper).

# STARTING SITUATION

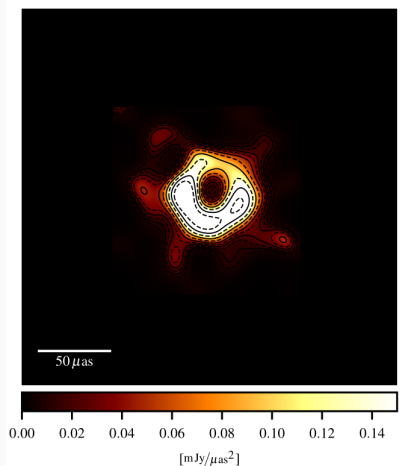
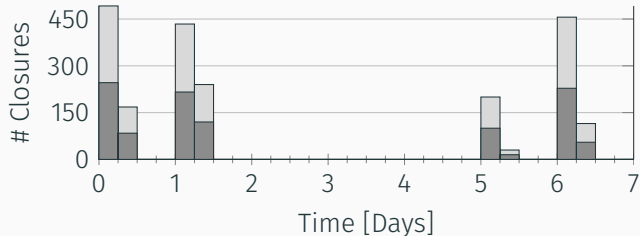


Figure 1: M87\* on day 0 imaged with ehtimaging [AAA<sup>+</sup>19b]. Saturated color bar.

- ✦ Uncertainty quantification via multiple independent imaging teams
- ✦ Independent imaging for each observing day



## Product Rule of Probabilities

aka **Bayes' theorem**

$$\mathcal{P}(s|d) = \frac{\mathcal{P}(d|s) \mathcal{P}(s)}{\mathcal{P}(d)}$$

$\mathcal{P}(A|B)$ : conditional probability,  
s: parameters, d: data.

## (Some) assumptions

- ✦ The brightness is **strictly positive**.
- ✦ The source features **correlation** in spatial, temporal and frequency direction.

⇒ Encoded in  $\mathcal{P}(s)$ .

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In our case

- ✦ Correlation structure  $\rightarrow$  full 4d-movie: sky brightness has shape (2, 28, 256, 256).
- ✦ The posterior  $\mathcal{P}(s|d)$  is a ridiculously high-dimensional function:

$$\begin{cases} \mathbb{R}^{7.500.000} & \rightarrow \mathbb{R}^{\geq 0} \\ s & \mapsto \mathcal{P}(s|d) \end{cases}$$

- ✦ This function encodes our knowledge on M87\* including **uncertainties**.

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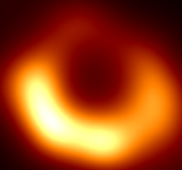


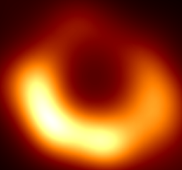


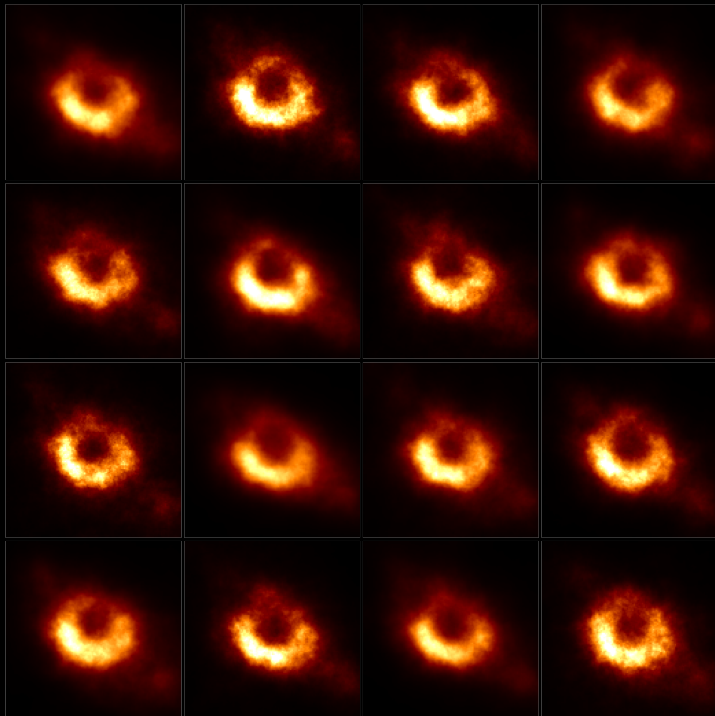












vlbi-resolve, [AFH<sup>+</sup>20], 16 posterior samples.

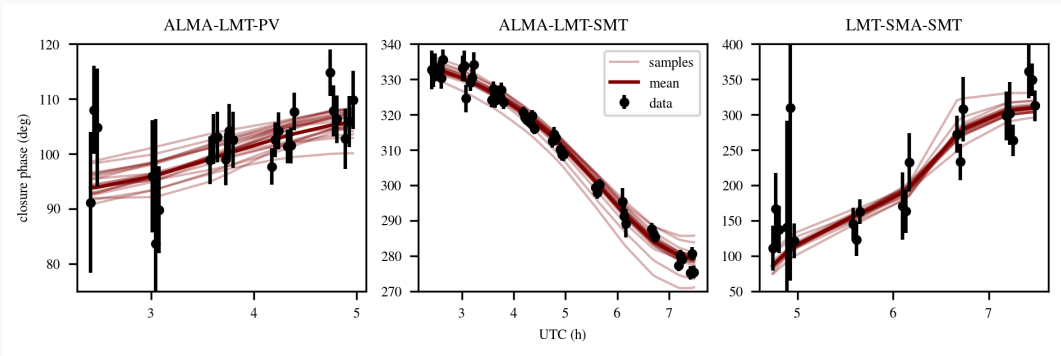


Figure 2: Three closure phases for triples of antennas as a function of time.

# RING FITTING (SEE [AAA<sup>+</sup>19B, TABLE 7])

	$d\ (\mu\text{as})$	$w\ (\mu\text{as})$	$\eta\ (^{\circ})$	$A$	$f_c$
EHT-IMAGING [AAA <sup>+</sup> 19b]					
April 5	$39.3 \pm 1.6$	$16.2 \pm 2.0$	$148.3 \pm 4.8$	$0.25 \pm 0.02$	0.08
April 6	$39.6 \pm 1.8$	$16.2 \pm 1.7$	$151.1 \pm 8.6$	$0.25 \pm 0.02$	0.06
April 10	$40.7 \pm 1.6$	$15.7 \pm 2.0$	$171.2 \pm 6.9$	$0.23 \pm 0.03$	0.04
April 11	$41.0 \pm 1.4$	$15.5 \pm 1.8$	$168.0 \pm 6.9$	$0.20 \pm 0.02$	0.04
OUR METHOD					
UNCERTAINTY AS PER [AAA <sup>+</sup> 19B, TABLE 7])					
April 5	$44.4 \pm 3.4$	$23.2 \pm 5.2$	$164.9 \pm 9.5$	$0.26 \pm 0.04$	0.365
April 6	$44.4 \pm 2.9$	$23.3 \pm 5.4$	$161.7 \pm 5.6$	$0.24 \pm 0.04$	0.374
April 10	$44.8 \pm 2.8$	$23.0 \pm 5.0$	$176.7 \pm 9.8$	$0.22 \pm 0.03$	0.374
April 11	$44.6 \pm 2.8$	$22.8 \pm 4.8$	$180.1 \pm 10.4$	$0.22 \pm 0.03$	0.372
SAMPLE UNCERTAINTY					
April 5	$44.1 \pm 1.2$	$23.1 \pm 2.4$	$163.9 \pm 5.0$	$0.25 \pm 0.03$	$0.377 \pm 0.081$
April 6	$44.0 \pm 1.2$	$22.9 \pm 2.4$	$161.9 \pm 6.0$	$0.24 \pm 0.03$	$0.385 \pm 0.085$
April 10	$44.6 \pm 1.2$	$22.9 \pm 2.5$	$176.2 \pm 6.5$	$0.22 \pm 0.03$	$0.383 \pm 0.089$
April 11	$44.6 \pm 1.2$	$23.0 \pm 2.6$	$179.8 \pm 6.2$	$0.22 \pm 0.03$	$0.383 \pm 0.090$

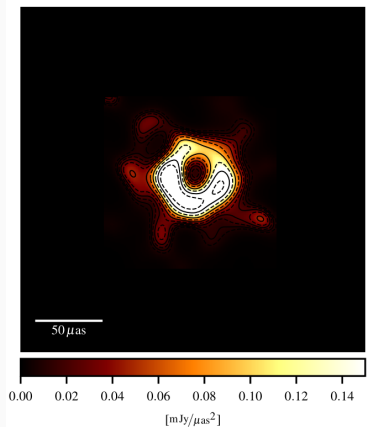


Figure 3: M87\* on day 0 imaged with ehtimaging [AAA+19b]. Saturated color bar.

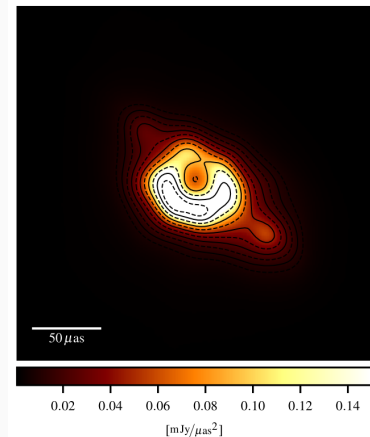


Figure 4: M87\* on day 0 imaged with our algorithm [AFH+20]. Saturated color bar.



## INFERENCE MODEL

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Product Rule of Probabilities aka Bayes' theorem

$$\mathcal{P}(s|d, \mathcal{M}) = \frac{\mathcal{P}(d|s, \mathcal{M}) \mathcal{P}(s|\mathcal{M})}{\mathcal{P}(d|\mathcal{M})}$$

Definitions:  $s$  := parameters,  $d$  := data,  $\mathcal{M}$ : model assumptions.

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Generative prior model:  $s(\xi) = F_M(\xi)$  with  $P(\xi) = \mathcal{N}(\xi|0, \mathbb{1})$

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PRIOR

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## Sky brightness distribution

$$S_{xt\nu} \quad x \in \Omega \subset \mathbb{R}^2, t \in I \subset \mathbb{R}, \nu \in V \subset \mathbb{R}^+$$

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$$S_{xt\nu} = e^{\tau_{xt\nu}}$$

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$$\langle \tau_{x,t,\nu} \tau_{x',t',\nu'} \rangle_{P(\tau)} = C(x, t, \nu, x', t', \nu')$$



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- Independent correlations
- Homogeneity and isotropy

$$\begin{aligned} S_{xt\nu} &= e^{\tau_{xt\nu}} \\ \langle \tau_{x,t,\nu} \tau_{x',t',\nu'} \rangle_{P(\tau)} &= C(x, t, \nu, x', t', \nu') \\ &= C^\Omega(x, x') C^I(t, t') C^V(\nu, \nu') \\ &= C^\Omega(|x - x'|) C^I(|t - t'|) C^V(|\nu - \nu'|) \end{aligned}$$

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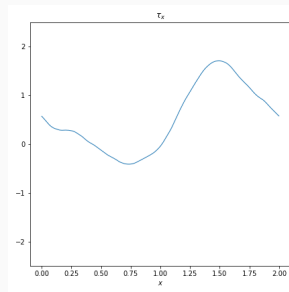
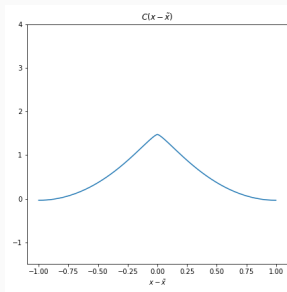
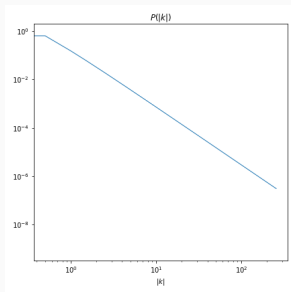
Uninformative

$$\Rightarrow P(\tau) = \mathcal{N}(\tau|0, C)$$

$$P^{(i)}(|k|) \quad i \in \{\Omega, I, V\}$$

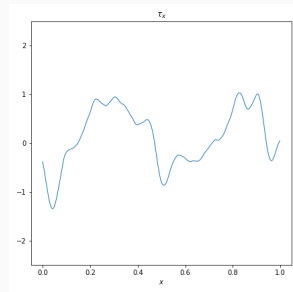
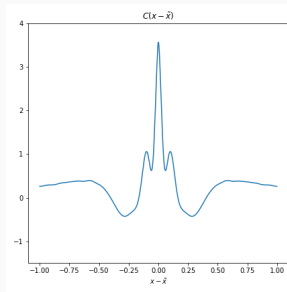
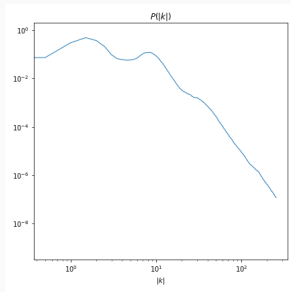
# PRIOR - CORRELATIONS

$$P^{(i)}(|k|) \propto |k|^{-\alpha} \quad i \in \{\Omega, I, V\}$$



# PRIOR - CORRELATIONS

$$P^{(i)}(|k|)$$

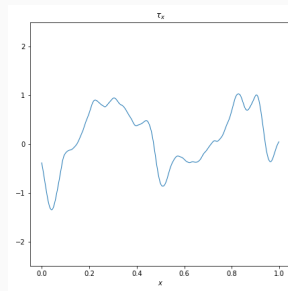
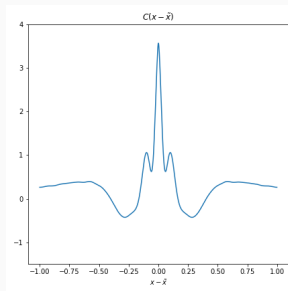
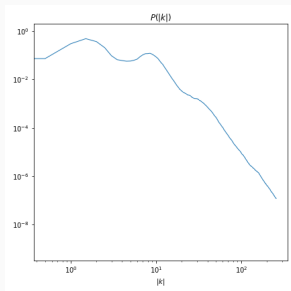


$$P^{(i)}(|k|) = e^{q(l)}$$

with  $l = \log(|k|)$

$$\frac{\partial^2 q}{\partial l^2} = \sigma \xi_q$$

$P(\xi_q) = \mathcal{N}(\xi_q | 0, 1)$  Integrated Wiener Process





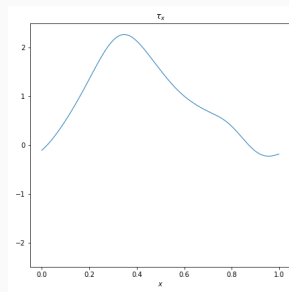
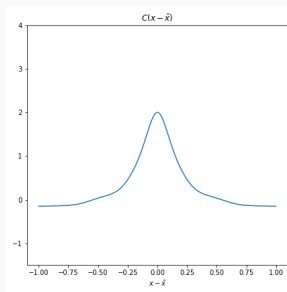
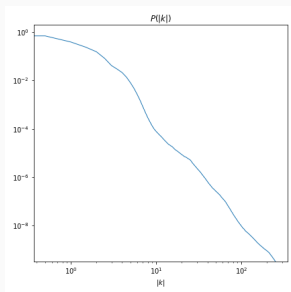
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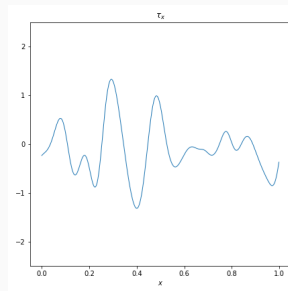
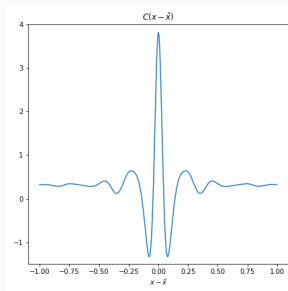
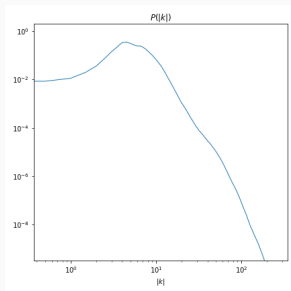
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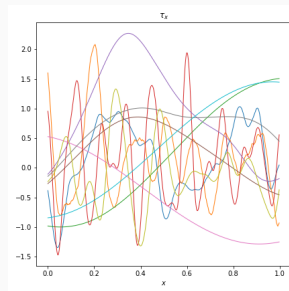
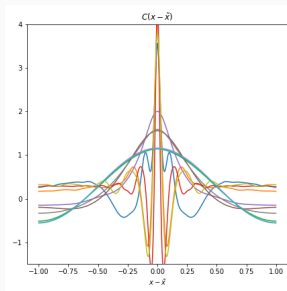
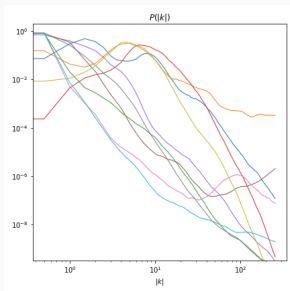
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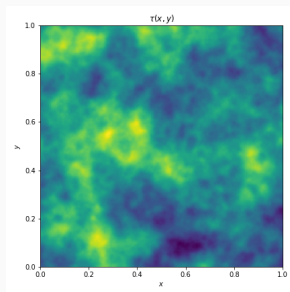
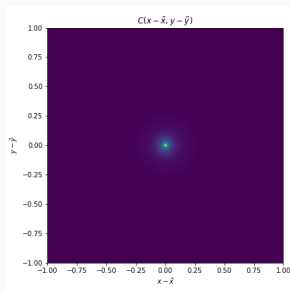
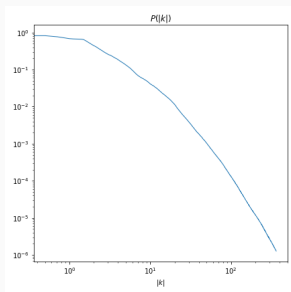
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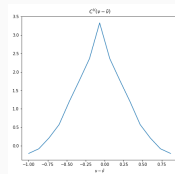
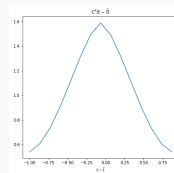
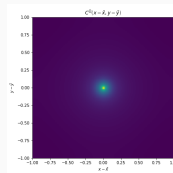
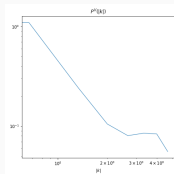
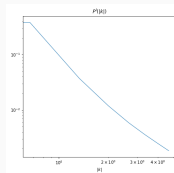
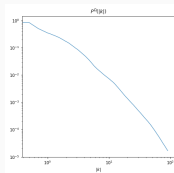
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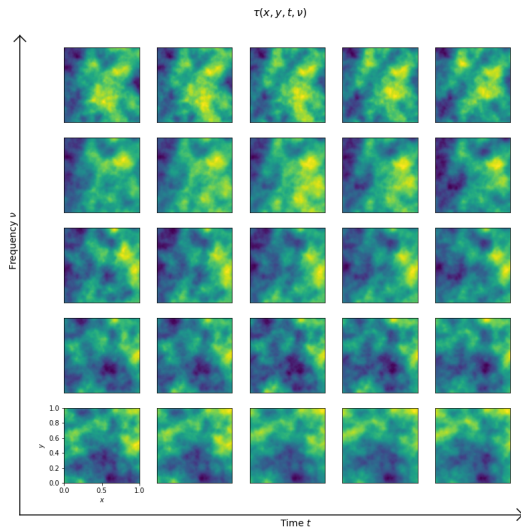
$$\frac{\partial^2 q}{\partial l^2} = \sigma \xi_q$$

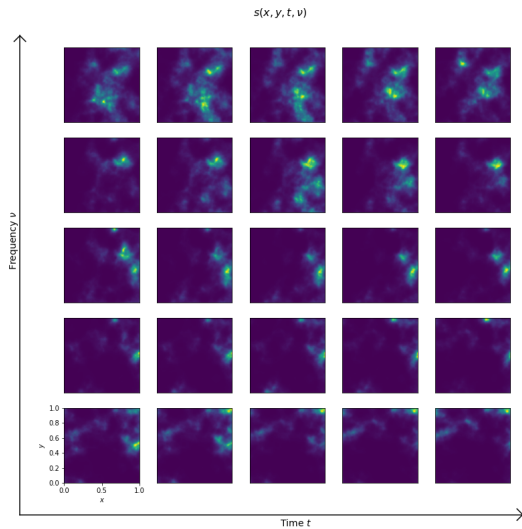
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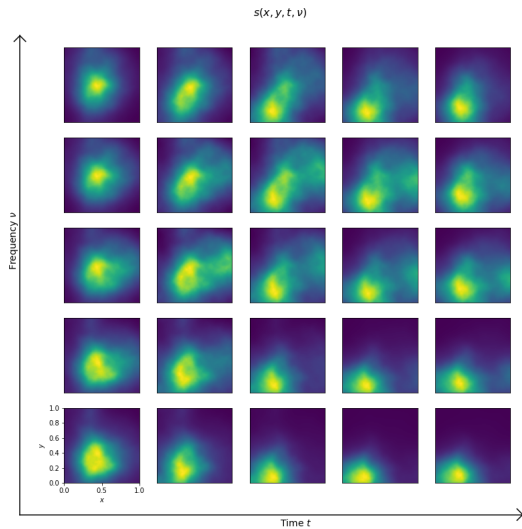


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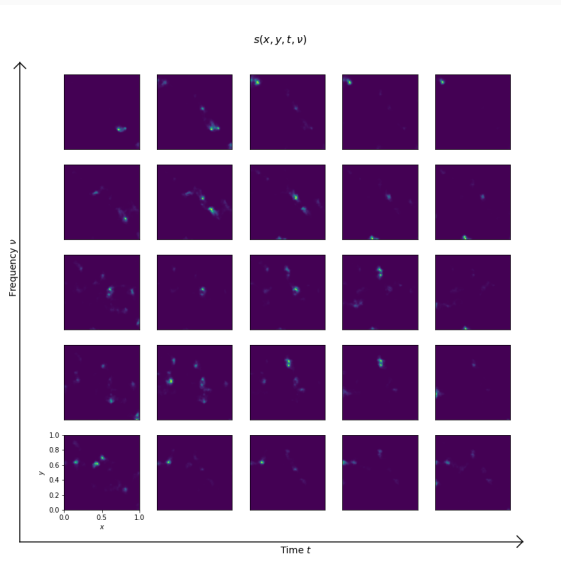


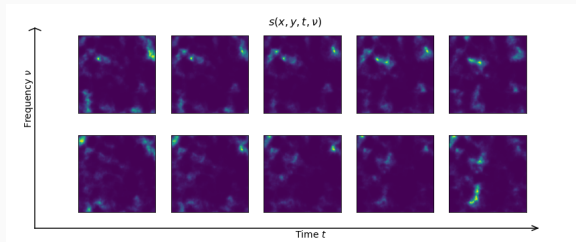


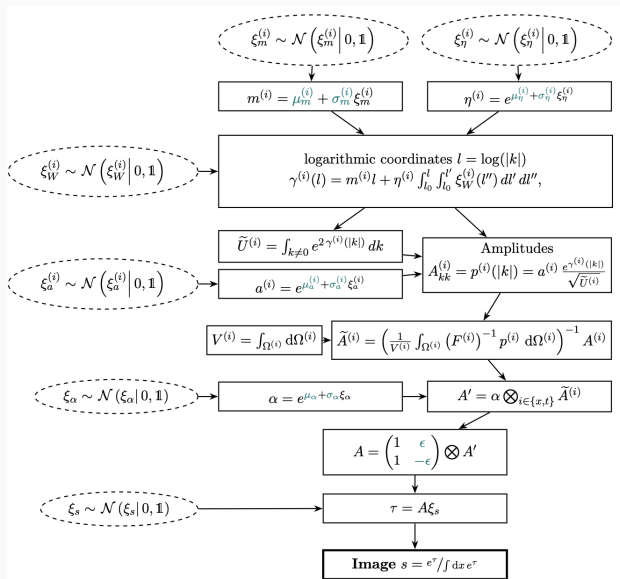








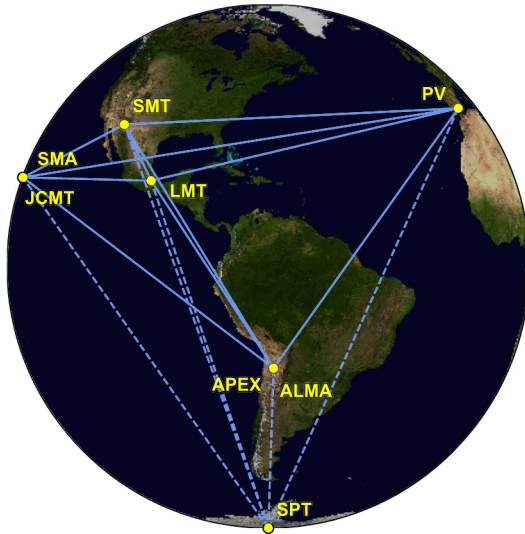




## LIKELIHOOD

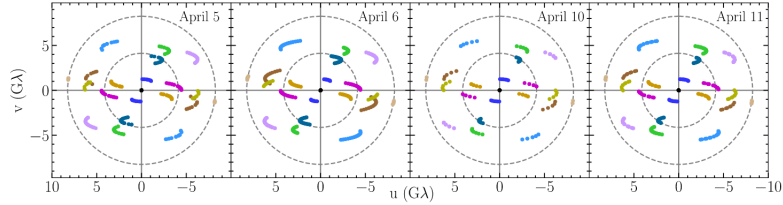
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# THE EVENT HORIZON TELESCOPE (EHT)



[AAA<sup>+</sup>19a]

# THE EVENT HORIZON TELESCOPE (EHT)



[AAA+19b]

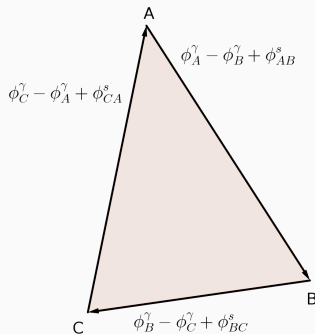
- ✦ Visibility data  $d$  and thermal noise level  $\sigma$  reported by [AAA<sup>+</sup>19a]

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- ✦ Direct imaging using visibilities is challenging for VLBI

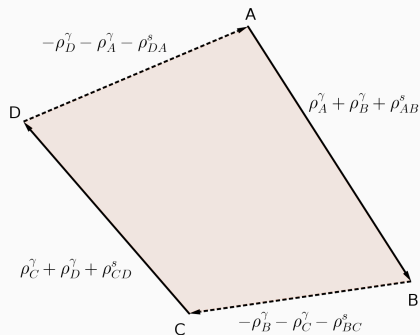


- ✦ Visibility data  $d$  and thermal noise level  $\sigma$  reported by [AAA<sup>+</sup>19a]
- ✦ Direct imaging using visibilities is challenging for VLBI

⇒ Imaging using closure quantities (phases  $\phi^d$  and logarithmic amplitudes  $\rho^d$ )



$$\phi_{\text{clos}}^d = M \phi^d$$



$$\rho_{\text{clos}}^d = L \rho^d$$

$$\mathcal{P}(\phi_{\text{clos}}^d | s) \approx \mathcal{N}(e^{i\phi_{\text{clos}}^d} | e^{i\phi_{\text{clos}}^s}, M N M^\dagger) \quad \text{with} \quad N = \text{diag}\left(\frac{\sigma^2}{|d|^2}\right)$$

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$$\mathcal{P}(\phi_{clos}^d | s) \approx \mathcal{N}(e^{i\phi_{clos}^d} | e^{i\phi_{clos}^s}, MNM^\dagger) \quad \text{with} \quad N = \text{diag}\left(\frac{\sigma^2}{|d|^2}\right)$$

$$\mathcal{P}(\rho_{clos}^d | s) \approx \mathcal{N}(\rho_{clos}^d | \rho_{clos}^s, LNL^\dagger)$$

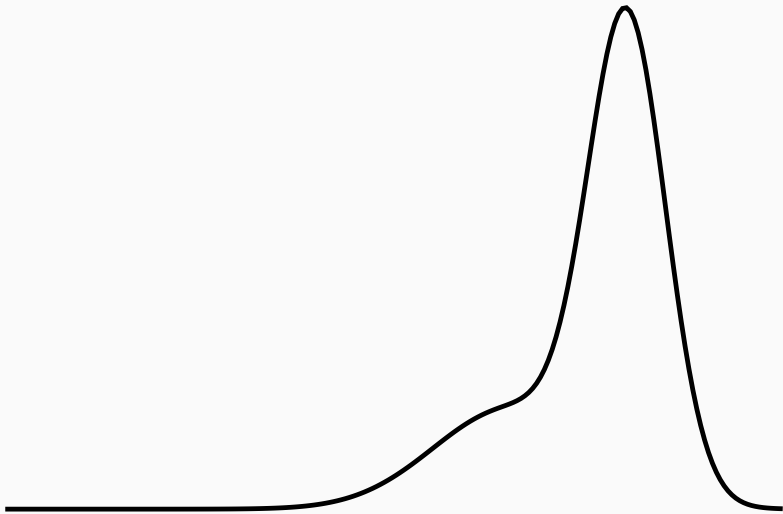
## Posterior distribution

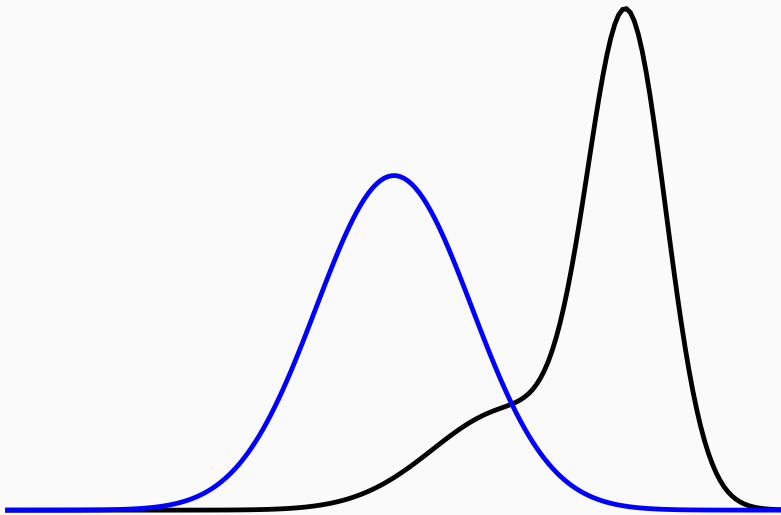
$$\mathcal{P}(\xi | \phi_{clos}^d, \rho_{clos}^d) \propto \mathcal{P}(\phi_{clos}^d | s(\xi)) \mathcal{P}(\rho_{clos}^d | s(\xi)) \mathcal{N}(\xi | 0, \mathbf{1})$$

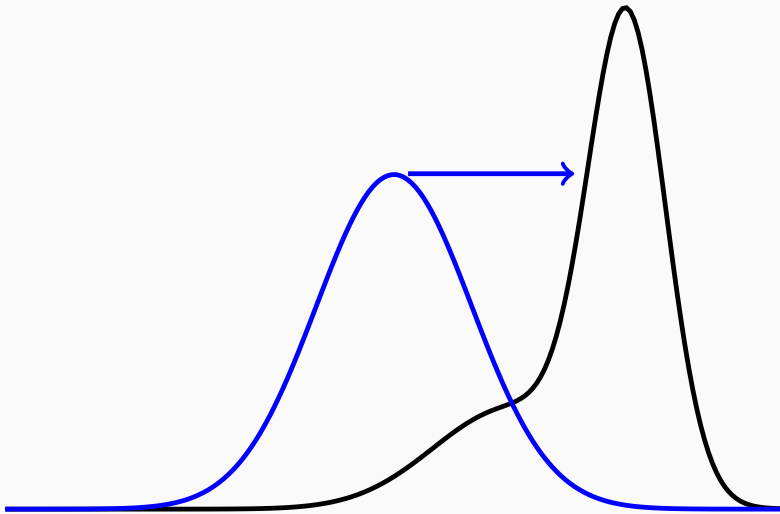
with generative prior  $s(\xi) = F_M(\xi)$

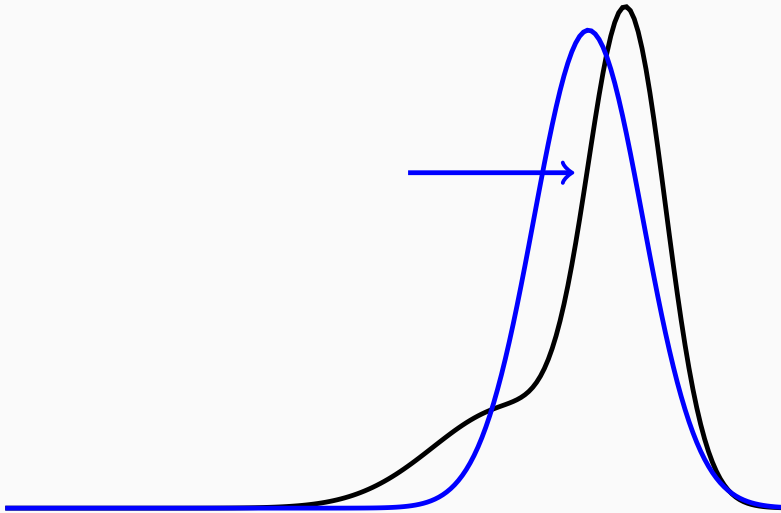
# METRIC GAUSSIAN VARIATIONAL INFERENCE

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## Kullback-Leibler Divergence

$$\mathcal{D}_{\text{KL}}(\mathcal{Q}_{\eta}(\xi) || \mathcal{P}(\xi|d)) = \int d\xi \mathcal{Q}_{\eta}(\xi) \ln \frac{\mathcal{Q}_{\eta}(\xi)}{\mathcal{P}(\xi|d)}$$

$$Q_{\eta}(\xi) = \mathcal{N}(\xi | \bar{\xi}, \Xi)$$

$$Q_{\eta}(\xi) = \mathcal{N}(\xi | \bar{\xi}, \Xi)$$

$$\Xi = \begin{pmatrix} \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot \end{pmatrix}$$

full-covariance

$$Q_{\eta}(\xi) = \mathcal{N}(\xi | \bar{\xi}, \Xi)$$

$$\Xi = \begin{pmatrix} \ddots & & & \\ & \ddots & & \\ & & \ddots & \\ & & & \ddots \end{pmatrix}$$

mean-field

$$Q_{\eta}(\xi) = \mathcal{N}(\xi | \bar{\xi}, \Xi)$$

$$\Xi(\xi) = (J(\xi)^{\dagger} l_d(\theta) J(\xi) + \mathbb{1})^{-1}$$

inverse Fisher metric

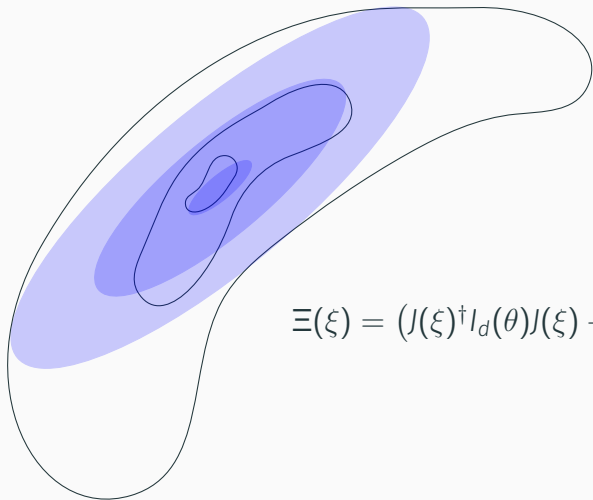
$$Q_\eta(\xi) = \mathcal{N}(\xi | \bar{\xi}, \Xi)$$

$$\Xi(\xi) = (J(\xi)^\dagger l_d(\theta) J(\xi) + \mathbb{1})^{-1}$$

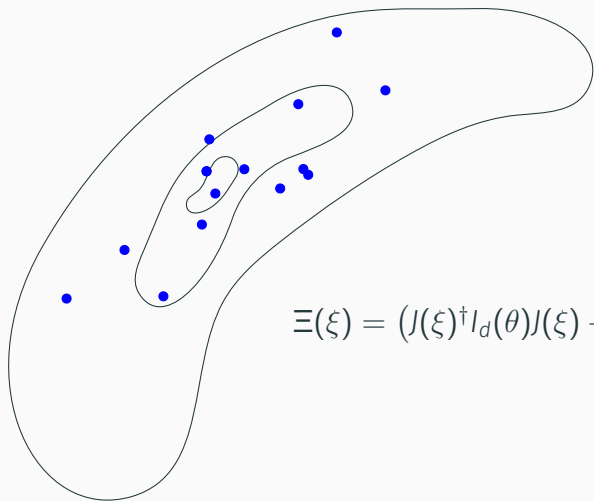
inverse Fisher metric

$$J(\xi) = \frac{\partial \theta(\xi)}{\partial \xi}$$

$$l_d(\theta) = \left\langle \frac{\partial \mathcal{H}(d|\theta)}{\partial \theta} \frac{\partial \mathcal{H}(d|\theta)}{\partial \theta^\dagger} \right\rangle_{\mathcal{P}(d|\theta)}$$

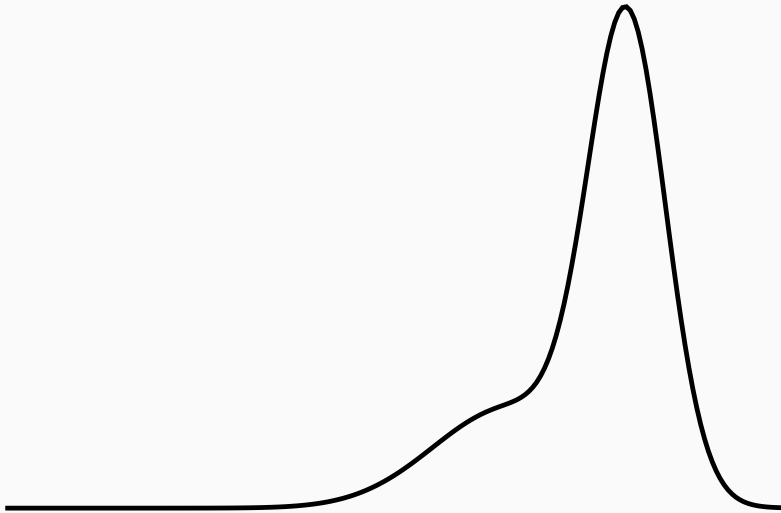


$$\Xi(\xi) = (J(\xi)^\dagger I_d(\theta) J(\xi) + \mathbb{1})^{-1}$$

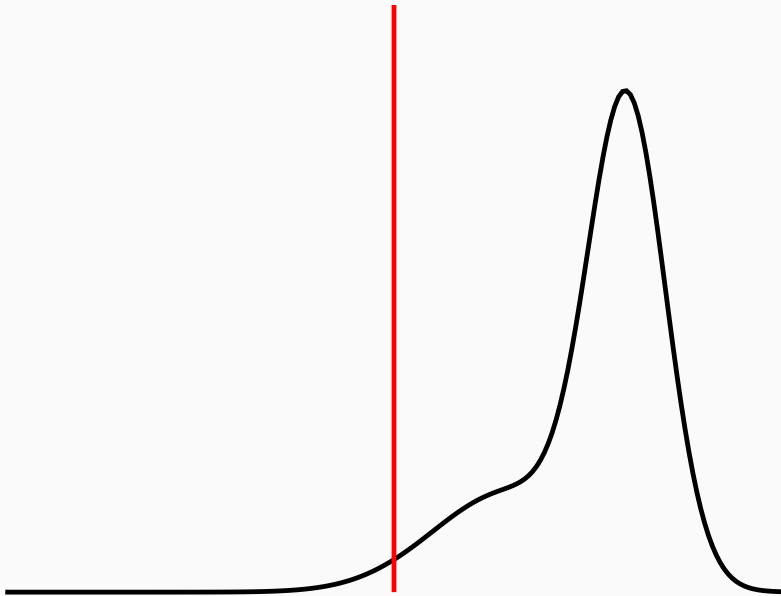


$$\Xi(\xi) = (J(\xi)^\dagger I_d(\theta) J(\xi) + \mathbb{1})^{-1}$$

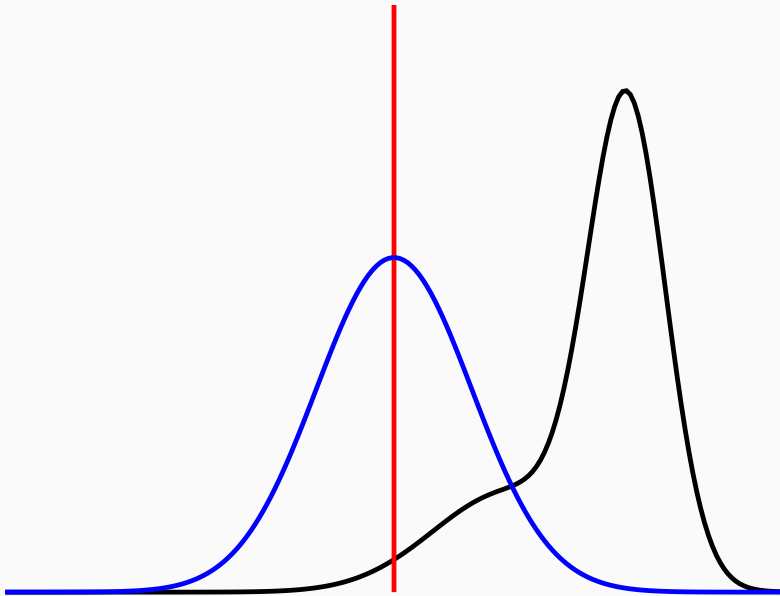




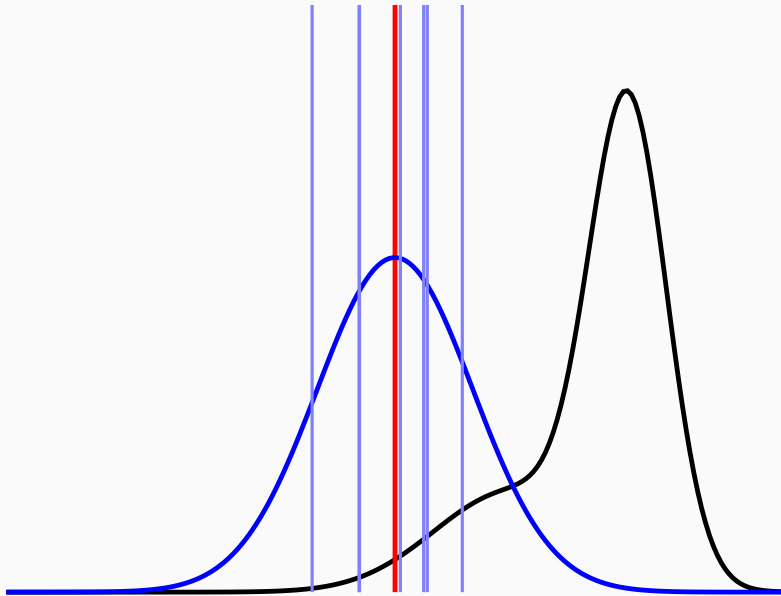
## METRIC GAUSSIAN VARIATIONAL INFERENCE



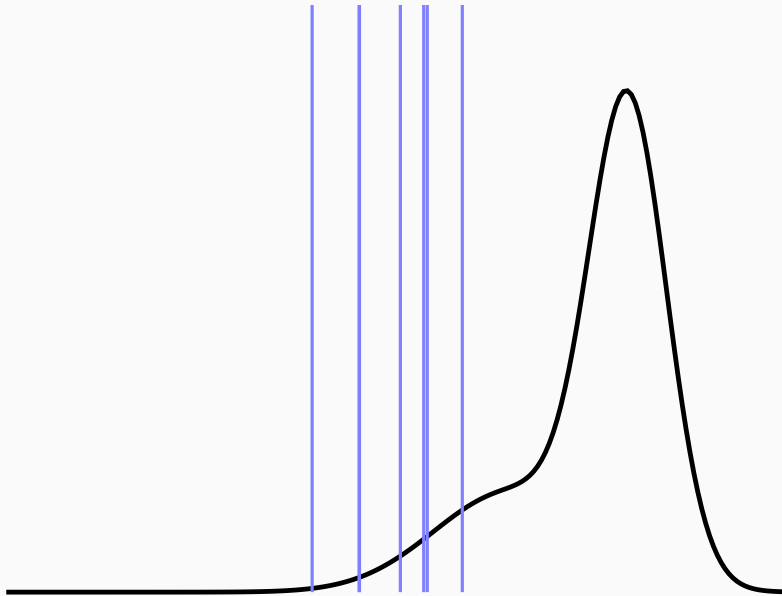
## METRIC GAUSSIAN VARIATIONAL INFERENCE



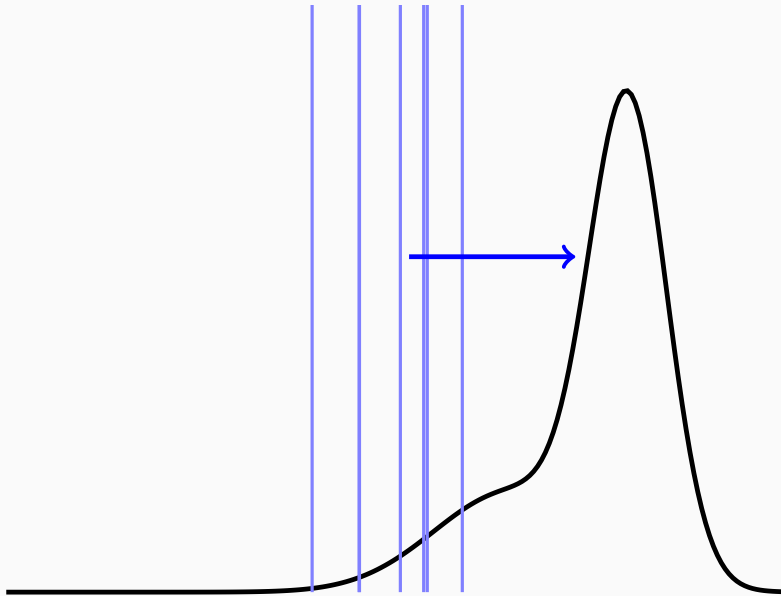
## METRIC GAUSSIAN VARIATIONAL INFERENCE



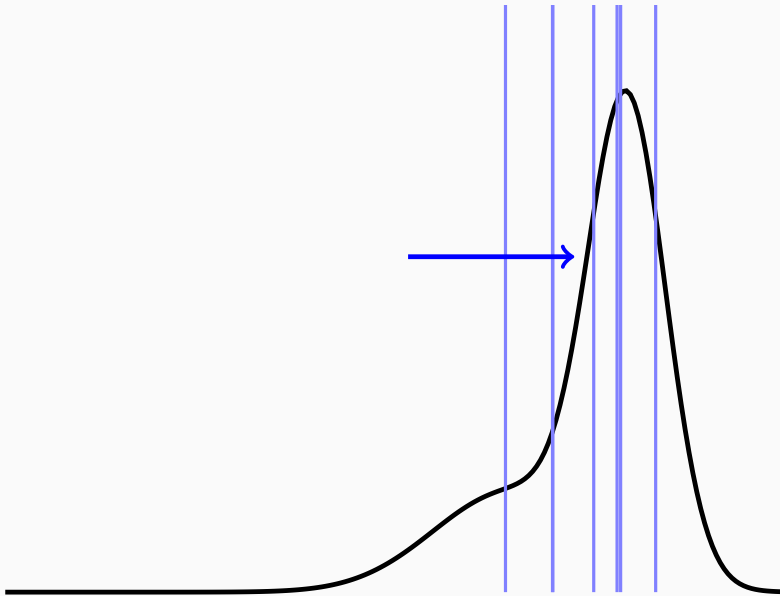
# METRIC GAUSSIAN VARIATIONAL INFERENCE

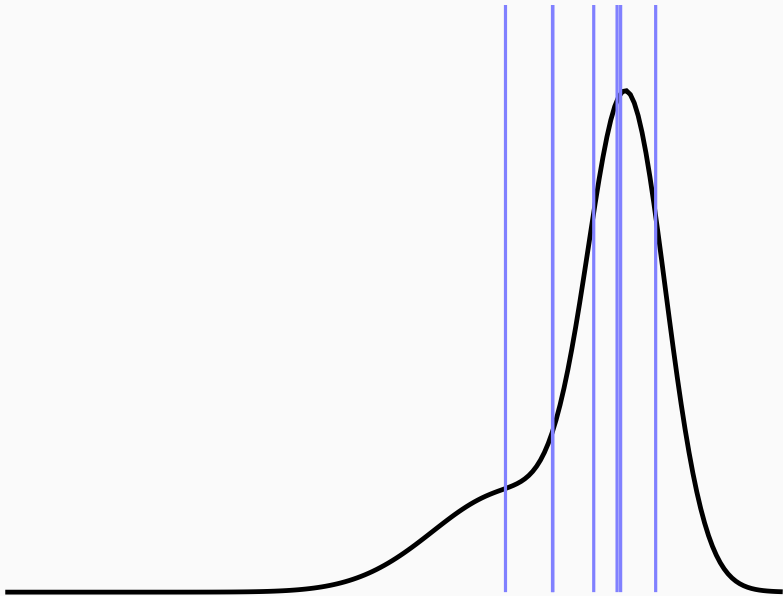


# METRIC GAUSSIAN VARIATIONAL INFERENCE



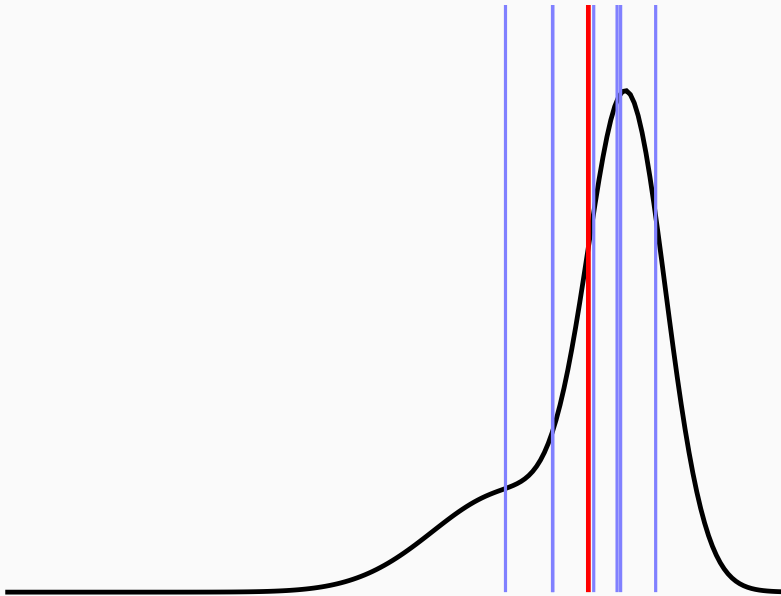
# METRIC GAUSSIAN VARIATIONAL INFERENCE

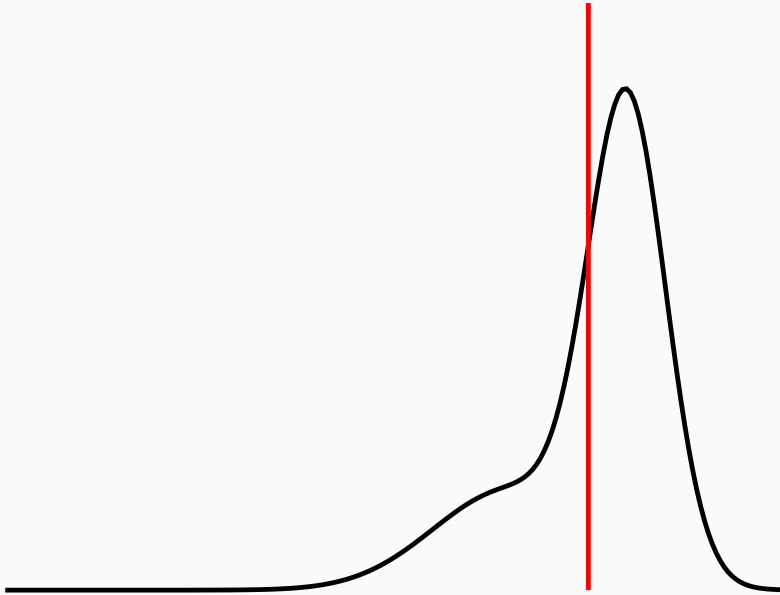


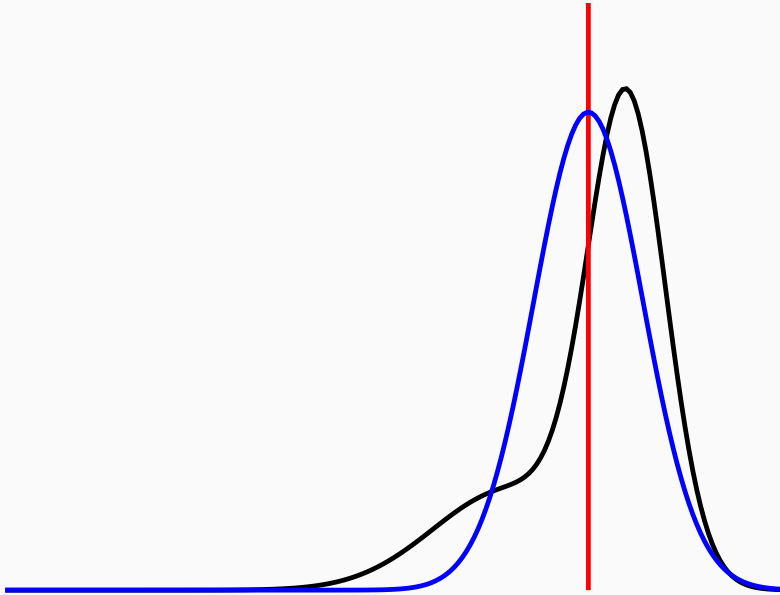




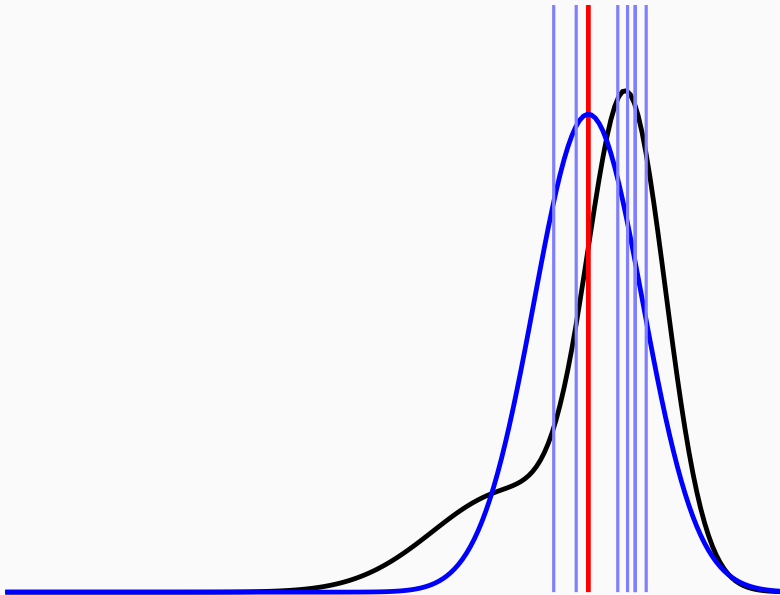
# METRIC GAUSSIAN VARIATIONAL INFERENCE

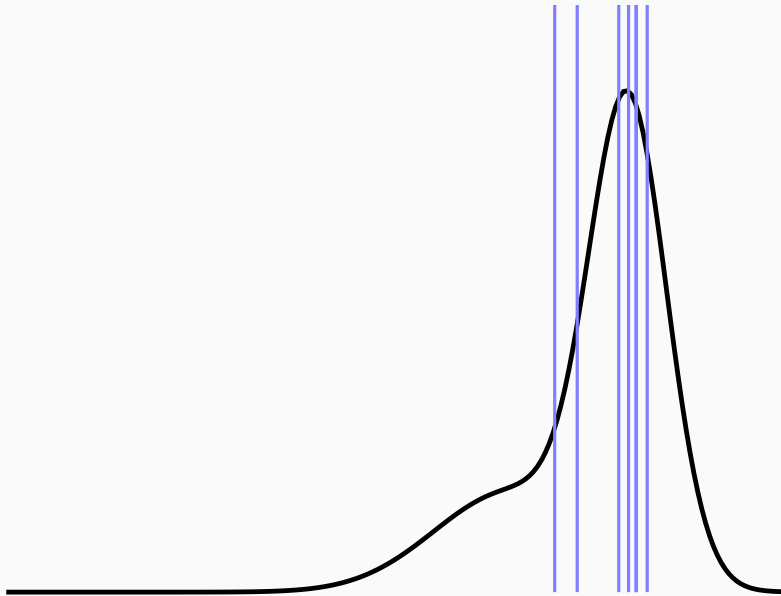




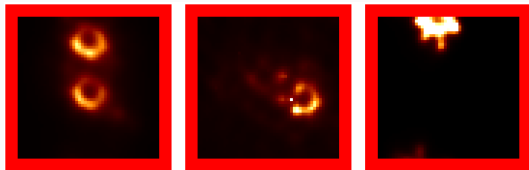


# METRIC GAUSSIAN VARIATIONAL INFERENCE






- ✦ Nonlinear optimization
- ✦ Stochastic loss function
- ✦ No absolute source position or brightness
- ✦ Multi-modality
  - ✦ Multiple source copies
  - ✦ “Source Teleportation”



# INFERENCE HEURISTIC

- ✦ Initially fit model to Gaussian shape
- ✦ Start with data of the first two days
- ✦ Alternate between phase and amplitude likelihood
- ✦ Reduce stochasticity of loss towards the end

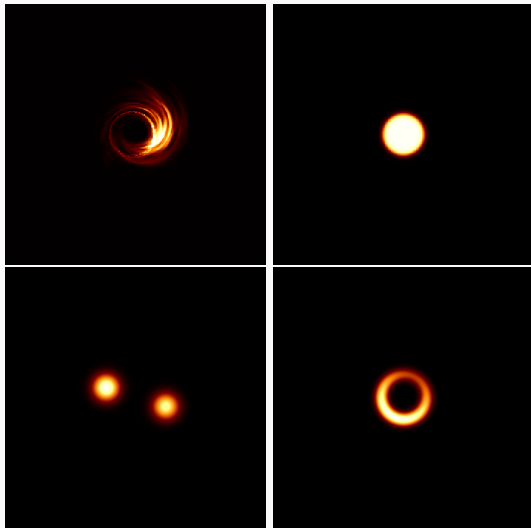
Iteration	Data Set	Tempering	Optimizer	Sample Pairs
$i = 0$	$i \geq 0$	$i \geq 0$	$i \geq 0$	$i \geq 0$
	first two days	full likelihood	V-LBFGS $4 * (4 + i//4)$ iterations	$N = 10 * (1 + i//8)$
		$i \geq 10$		
	$i \geq 30$	alternating		
	all days	$i \geq 50$	$i \geq 50$	
$i = 59$		full likelihood	Natural Gradient 20 iterations	

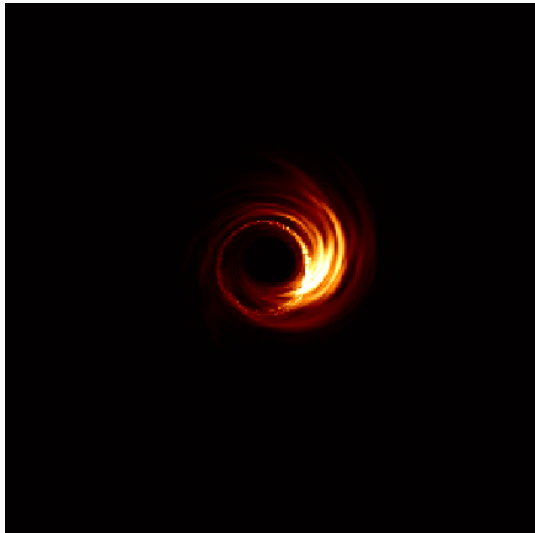
## VALIDATION

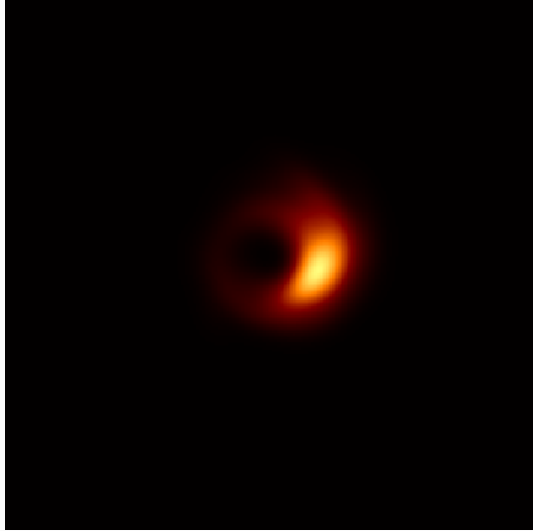
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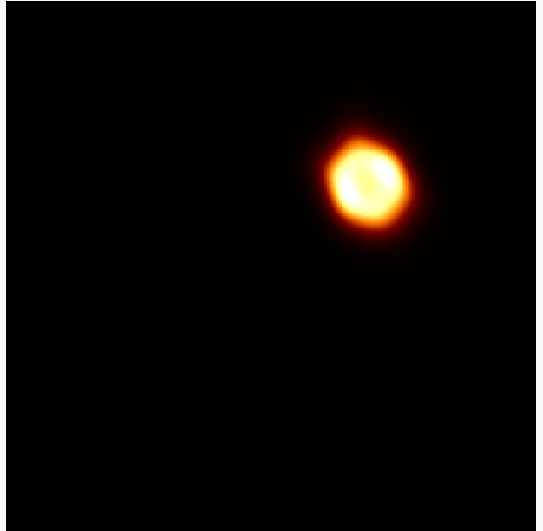
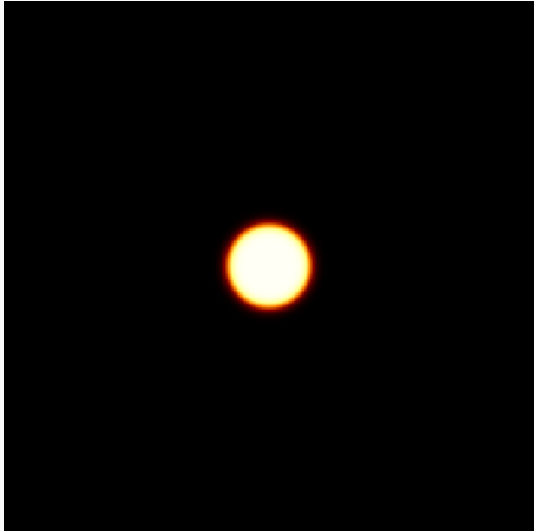


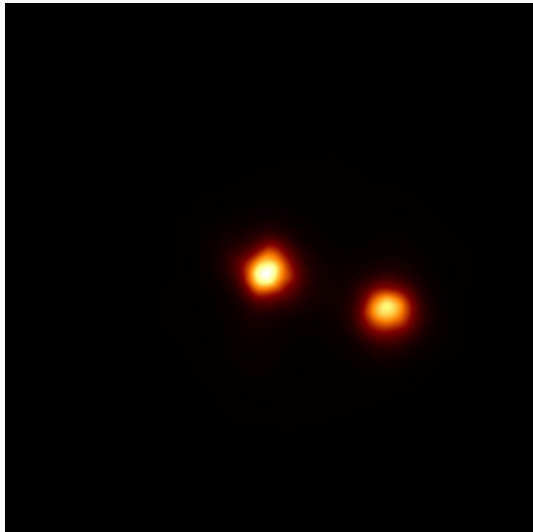
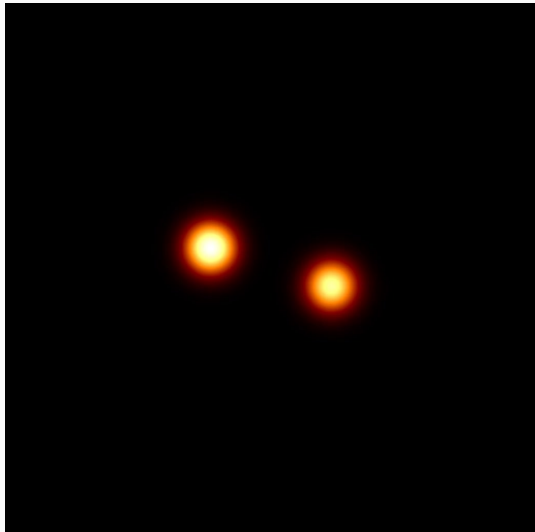
- ✦ Synthetic source
- ✦ Generate data according to EHT observation
- ✦ Reconstruct
- ✦ Compare to truth

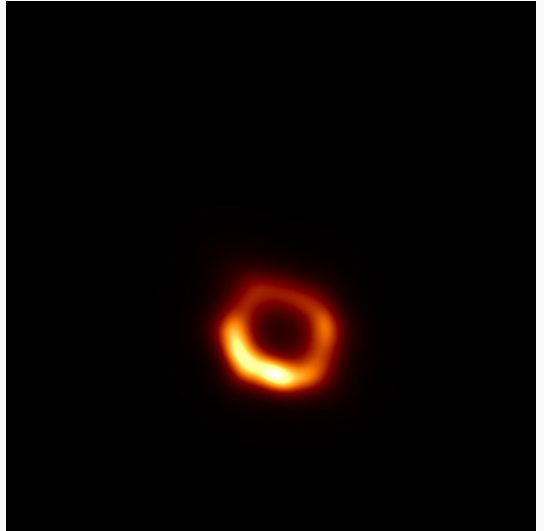
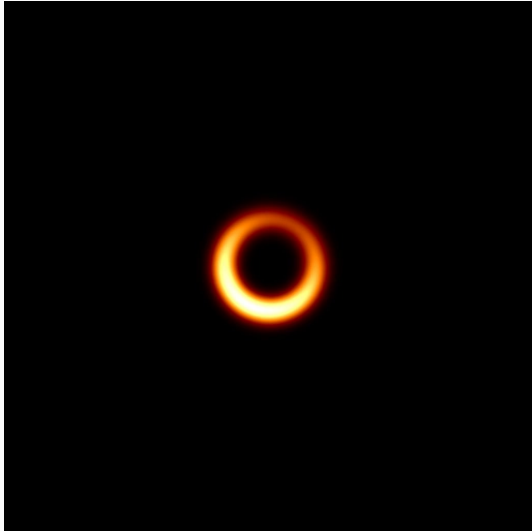






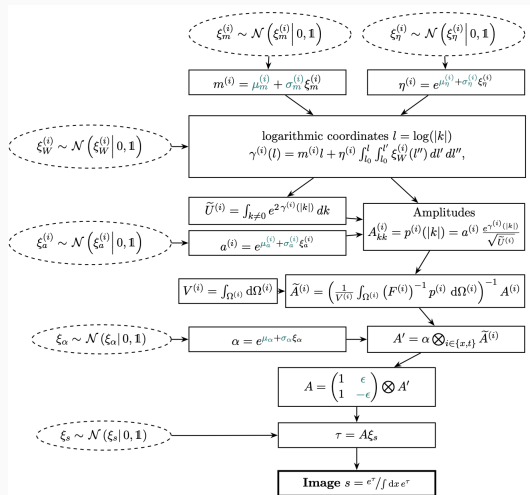






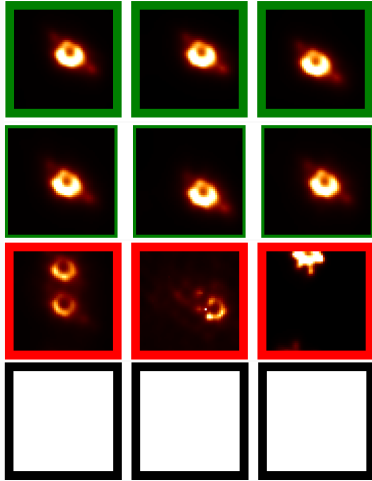
# HYPERPARAMETER VALIDATION

- ✦ In total 15 hyperparameters
- ✦ Specifying mean and variance
- ✦ Draw mean hyperparameters within a uniform  $3\sigma$  interval
- ✦ Perform 100 reconstructions

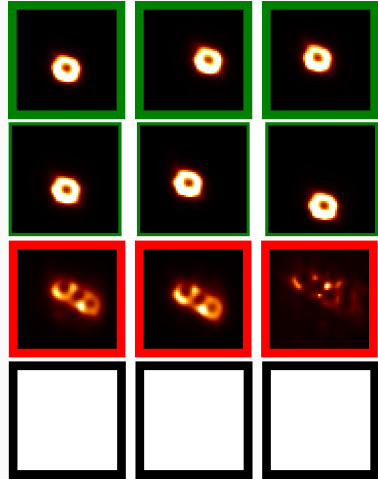


# THE GOOD, THE BAD AND THE UGLY

M87\*

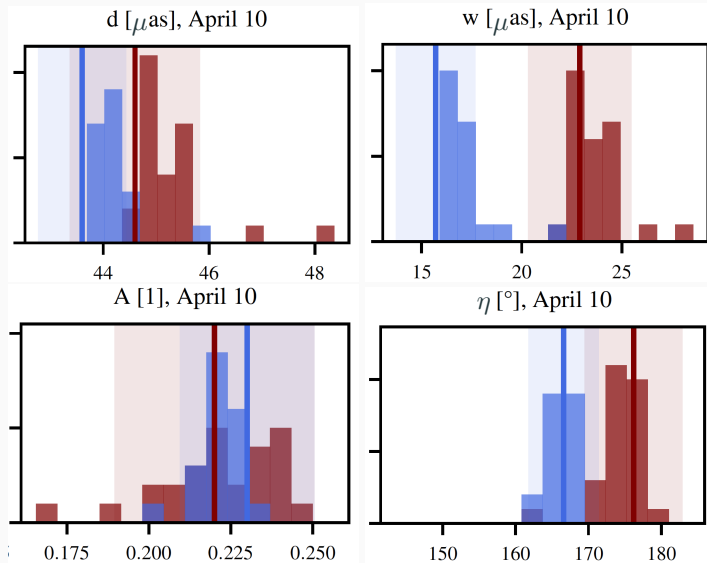


Crescent





# RING PARAMETERS



- ✦ Reconstruction works on various sources
- ✦ We recover dynamics
- ✦ Results are widely insensitive to hyperparameters
- ✦ Room for improvement in the inference heuristic



## CONCLUSION

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# CONCLUSION

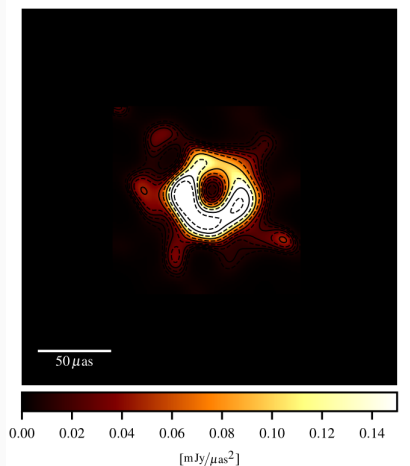


Figure 5: M87\* on day 0 imaged with ehtimaging [AAA<sup>+</sup>19b]. Saturated color bar.

## Differences to [AAA<sup>+</sup>19b]

- ✦ Uncertainty quantification via multiple independent imaging teams
- ✦ Independent imaging for each observing day

# CONCLUSION

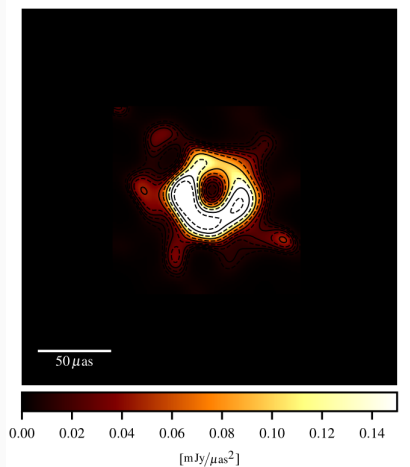


Figure 5: M87\* on day 0 imaged with ehtimaging [AAA<sup>+</sup>19b]. Saturated color bar.

## Differences to [AAA<sup>+</sup>19b]

- ✦ Intrinsic uncertainty quantification
- ✦ Independent imaging for each observing day

# CONCLUSION

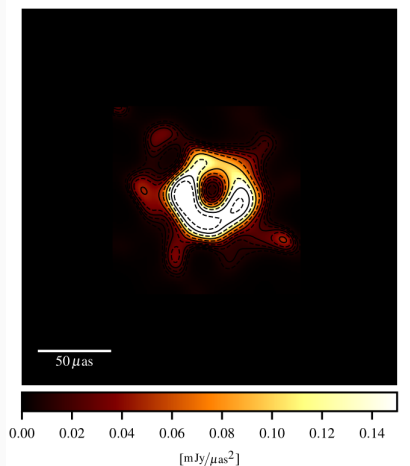


Figure 5: M87\* on day 0 imaged with ehtimaging [AAA<sup>+</sup>19b]. Saturated color bar.

## Differences to [AAA<sup>+</sup>19b]

- ✦ Intrinsic uncertainty quantification
- ✦ Temporal correlations → full 4d-movie

# CONCLUSION

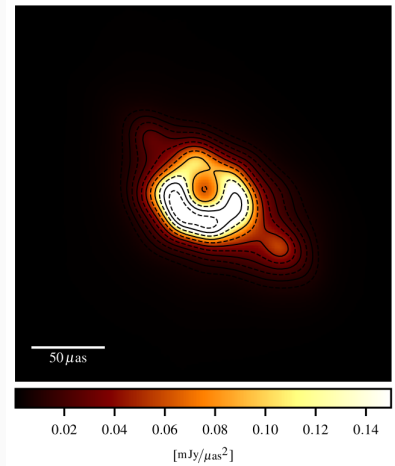


Figure 5: M87\* on day 0 imaged with vlbi-resolve [AFH<sup>+</sup>20]. Saturated color bar.

## Differences to [AAA<sup>+</sup>19b]

- ✦ Intrinsic uncertainty quantification
- ✦ Temporal correlations → full 4d-movie

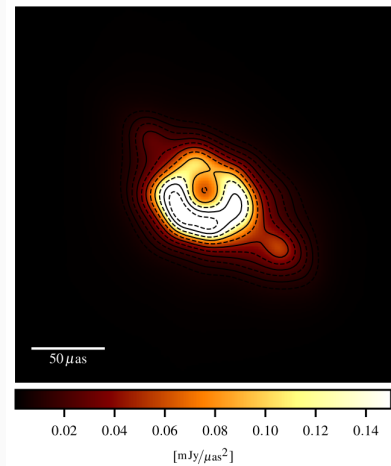


Figure 5: M87\* on day 0 imaged with vlbi-resolve [AFH<sup>+</sup>20]. Saturated color bar.

## Differences to [AAA<sup>+</sup>19b]

- ✦ Intrinsic uncertainty quantification
- ✦ Temporal correlations → full 4d-movie

## Some aspects

- ✦ Four-dimensional (time, frequency, space) reconstruction of M87\*
- ✦ Correlation kernel is non-parametrically learned from the data
- ✦ Bayesian treatment despite huge problem size ( $10^7$  dofs)

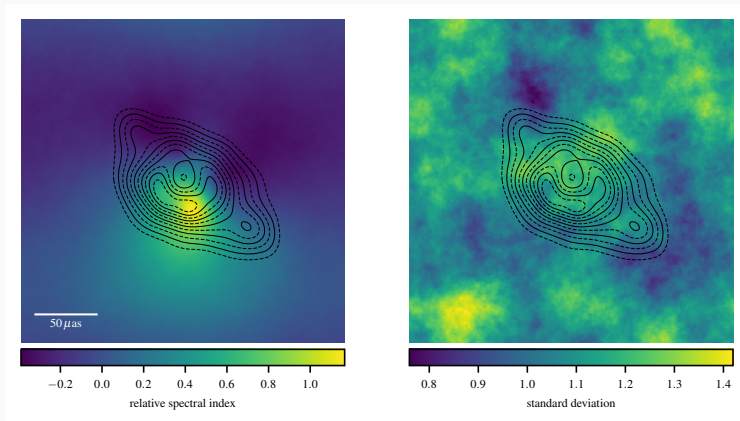


QUESTIONS? DISCUSSION!

## REFERENCES

-  Kazunori Akiyama, Antxon Alberdi, Walter Alef, Keiichi Asada, Rebecca Azulay, Anne-Kathrin Baczko, David Ball, Mislav Baloković, John Barrett, Dan Bintley, et al.  
**First M87 Event Horizon Telescope Results. I. The Shadow of the Supermassive Black Hole.**  
*The Astrophysical Journal Letters*, 875(1):L1, April 2019.
-  Kazunori Akiyama, Antxon Alberdi, Walter Alef, Keiichi Asada, Rebecca Azulay, Anne-Kathrin Baczko, David Ball, Mislav Baloković, John Barrett, Dan Bintley, et al.  
**First M87 Event Horizon Telescope Results. IV. Imaging the Central Supermassive Black Hole.**  
*The Astrophysical Journal Letters*, 875(1):L4, April 2019.
-  Philipp Arras, Philipp Frank, Philipp Haim, Jakob Knollmüller, Reimar Leike, Martin Reinecke, and Torsten Enßlin.  
**M87\* in space, time, and frequency.**  
*arXiv e-prints*, page arXiv:2002.05218, February 2020.

## SPECTRAL DEPENDENCY



**Figure 6:** The relative spectral index and the pixel-wise uncertainty, as calculated from the 227–229 GHz channels.

	April 5	April 6	April 10	April 11
Simulation	1.2, 1.0	1.3, 1.2	1.4, 1.3	1.1, 1.1
Disk	1.6, 1.2	1.4, 1.3	1.5, 1.4	1.3, 1.2
Double Sources	1.2, 1.1	1.2, 1.1	1.3, 1.3	1.4, 1.1
Crescent	1.2, 1.0	1.3, 0.9	1.0, 0.9	1.4, 1.1
M87*	1.1, 0.9	1.1, 0.8	1.1, 0.9	1.1, 0.9

**Table 1:** The  $\chi^2$  of the reconstruction for closure (phase, amplitude).